

## MCG DISTANCE-BASED TRAINING - APPLICATION NOTE#4

### **KM - Motor Constant - “THE GREAT EQUALIZER”**

One of the most often overlooked parameters of direct current motors (both brush and brushless) is the **Km** or motor constant. The motor constant or **Km defines the ability of the motor to transform electrical power to mechanical power** and is a valuable tool for the application engineer particularly for recommending a “best fit” replacement for a competitor’s motor. Although motor constant does not address thermal or other viscous losses, it is still useful for getting one into the “ballpark.” Regarding motor constant:

- ✚ Motor Constant is a **figure of merit used to compare the relative efficiencies and output power capabilities of different motors. Km defines the ability of the motor to transform electrical power to mechanical power.**
- ✚ Motor Constant is calculated by the following equation (in English units):
  - **$Km = Kt/\sqrt{Rt}$**  - where Kt is the torque sensitivity (oz.-in./amp) and Rt is the terminal resistance (ohms)
  - Units for Km are **oz.-in./ $\sqrt{watts}$**  (in English units)
- ✚ As can be seen from the above equation, the lower the motor’s resistance the higher the Km will be.
- ✚ **Physical motor size can be deceiving!** It is sort of intuitive to think a much larger motor will be more powerful than a smaller motor but this may not be the case. How then would we determine which is the more powerful motor? By calculating the motor constant.
- ✚ Customers are notorious for not providing complete specifications, making it difficult if not impossible to recommend a best fit alternative. However if we can get the customer to share the **KT** and **RT** of the motor, using the equation for calculating motor constant, we can make a relatively good recommendation.
- ✚ Knowing how to calculate motor constant is invaluable in trying to recommend a best fit equivalent for competitor’s units.

Now that the background is in place, let’s put this new-found knowledge to work:

#### **Example #1:**

Using the MCG Motor Catalog (and without peeking), calculate the motor constant for a BN23-28MG-01LH

This motor has a KT of 4.26 oz.-in./amp and a RT of 0.181 ohms.  $KM = KT/\sqrt{R} = 4.26 \text{ oz.-in./amp}/\sqrt{0.181 \text{ ohms}} = \mathbf{10.01 \text{ oz.-in./}\sqrt{watts}}$

**Example #2:**

A **C34-L70W10** is 3.16 inches in diameter and 7.0 inches long. The volume of this motor is **54.5 cubic inches**. (treating the motor as a cylinder). A **BN34-35AF-02LH** is 3.40 inches in diameter and 3.50 inches long. The volume of this motor is **31.7 cubic inches** (again treating the motor as a cylinder). The C34-L70W10 is obviously a much larger motor. Which motor however is more powerful?

Using KM, the C34-L70W10 has a KM of **20.82 oz.-in./√watts**. The BN34-35AF-02LH has a KM of **25.87 oz.-in./√watts**. From this you can see the much smaller motor is more powerful than the larger motor.

**Example #3:**

A customer comes in looking for a best fit replacement for a SLMTI motor. The motor data is as follows:



Winding Data at 48 VDC (Approximate)

PARAMETER	UNITS	VALUE
Torque Constant, $K_t$	oz-in/A	<b>5.9</b>
Voltage Constant, $K_e$	V/kRPM	<b>4.37</b>
No Load Speed, NLS	RPM	<b>10992</b>
Electrical Time Constant, $t_e$	mS	<b>0.43</b>
Mechanical Time Constant, Sensorless, $t_m$	mS	<b>6.01</b>
Mechanical Time Constant, w/Halls, $t_m$	mS	<b>6.46</b>
Resistance at 25°C, $R_m$	Ohm	<b>2.34</b>
Inductance, $L_m$	mH	<b>0.99</b>
Max. Continuous Power Output at 100°C Rise	W	<b>78.59</b>
Max. Continuous Torque Output at 100°C Rise	oz-in	<b>11.07</b>
Max. Continuous Speed Output at 100°C Rise	RPM	<b>959</b>

What MCG brushless motor would you recommend as a best fit replacement?

Using KM as a figure of merit, we see the SLMTI motor has a  $K_T$  of 5.9 oz.-in./amp and a  $R_T$  of 2.34 ohms. Calculating KM we find this motor has a **KM of 3.86 oz.in./√watts**. When we recommend an

alternative motor we want to match the KM as closely as possible - to insure the power is equivalent - as well as match the KT as closely as possible - to insure the speed is equivalent. So I'm going to look for a brushless motor with a KM as close to 3.86 oz.-in./√watts and a KT as close to 5.9 oz.-in./amp as possible. My recommendation would be:

**BN23-13MG-03LH** - this motor has a KT of 5.18 oz.-in./amp and a KM of 3.77 oz.-in./√watts.

The customer may need a slight winding adjustment to get closer but this is a good baseline from which to start.

**Example #4:**

You might want to try this one on your own! A customer has sent in the following data for a Bodine **brush motor** but wants to replace it with a **brushless motor**. What brushless motor would you recommend? (Caution - look at the units - conversions may be necessary!):

**Specifications**

Model Number	6230 <a href="#">[CAD Drawings]</a>
Category	180V, Metric Mounting Provisions
Speed (rpm)	3000
Rated Torque (Nm)	.50
Amps	1.1
Motor Watts	155
KT (Nm/A)	.52
KE (V/krpm)	53
Winding Resistance (ohms)	15.9
Winding Inductance (mH)	N/A
Armature Inertia (kg-mm <sup>2</sup> )	270
Radial Load (N)	240
Length XH (mm)	158.9
Weight (kg)	3.1
Product Type	33A5BEPM
Winding	180V
Accessory Shaft	NO
Connection Diagram	074 10097

In recapping KM - Motor Constant:

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- ✚ As can be seen from the above equation, the lower the motor's resistance the higher the  $K_m$  will be.
- ✚ **Physical motor size can be deceiving!** It is sort of intuitive to think a much larger motor will be more powerful than a smaller motor but this may not be the case. How then would we determine which is the more powerful motor? By calculating the motor constant.

Hope this was helpful! More to come....

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1/16/2008